

```

0001      RFAL MX,MZ
0002      READ(5,100)S,OY

0003      Z=0.0
0004      X=0.0
0005      TWIST=0.0
0006      ZANG=0.0
0007      XANG=0.0
0008      ANGZ=0.0
0009      ANGX=0.0

C      DEFLECTIONS AND TWISTS INITIALIZED TO ZERO AT THE WING ROOT
C
C      STARTING AT THE WING ROOT THE WING IS DIVIDED INTO AS MANY SECTIONS AS
C      DESIRED FOR ACCURACY. EACH SECTION IS TREATED AS A FREEBODY OF CONSTANT
C      CROSSSECTION. THE DEFLECTIONS FOR EACH SECTION DUE TO MOMENT AND SHEAR LOADS
C      WERE ACCUMULATED USING SUPERPOSITION AS THE PROGRAM PROGRESSED FROM THE
C      ROOT TO THE TIP. TWISTING DEFLECTIONS WERE CALCULATED FOR EACH SECTION AS A
C      FUNCTION OF THE SHEAR FLOW DISTRIBUTION IN THE SKIN DUE TO THE TORQUE LOAD.
C
0010      ICOUNT=0
0011      YLOCAT=0.0
0012      CALL SECT(VX,VZ,WX,WZ,TORO,E,G,XIBAR,ZIBAR,PMI,YLOCAT,ICOUNT,DY,WT
* ,MX,MZ,S,TPNT,TDISTR)
0013      WRITE(6,200)YLOCAT,Z,X,TWIST
0014      I YCOUNT=ICOUNT+1
0015      YLOCAT=YLOCAT+DY
0016      CALL SECT(VX,VZ,WX,WZ,TORO,E,G,XIBAR,ZIBAR,PMI,YLOCAT,ICOUNT,DY,WT
* ,MX,MZ,S,TPNT,TDISTR)
0017      ZDISTR=(W7*DY**4)/(8.*E*XIBAR)
0018      ZPNT=(VZ*DY**3)/(3.*E*XIBAR)
0019      ZMX=(MX*DY**2)/(2.*E*XIBAR)
0020      Z=ZDISTR+ZPNT+ZANG+ZMX+Z
0021      ANGZP=(VZ*DY**2)/(2.*E*XIBAR)
0022      ANGZD=(WZ*DY**3)/(6.*E*XIBAR)
0023      ANGMX=(MX*DY)/(E*XIBAR)
0024      ANGZ=ANGZP+ANGZD+ANGMX+ANGZ
0025      ZANG=DY*SIN(ANGZ)
0026      XDISTR=(WX*DY**4)/(8.*E*ZIBAR)
0027      XPNT=(VX*DY**3)/(3.*E*ZIBAR)
0028      XMZ=(-MZ*DY**2)/(2.*E*ZIBAR)
0029      X=XDISTR+XPNT+XANG+XMZ+X
0030      ANGXP=(VX*DY**2)/(2.*E*ZIBAR)
0031      ANGXD=(WX*DY**3)/(6.*E*ZIBAR)
0032      ANGMZ=(-MZ*DY)/(E*ZIBAR)
0033      ANGX=ANGXP+ANGXD+ANGMZ+ANGX
0034      XANG=DY*SIN(ANGX)
0035      TWIST=TDISTR+TPNT+TWIST
0036      WRITE(6,200)YLOCAT,Z,X,TWIST
0037      IF(YLOCAT.LT.S)GO TO 1
0038      CALL EXIT
0039      100 FORMAT(/,41X,F8.5/,30X,F7.4)
0040      200 FORMAT(1X,4(5X,E13.5))
0041      END

```

```
0001 FUNCTION FCN(Y,N)
0002 REAL LIFT
C
0003 C LIFT/IN AS A FUNCTION OF Y
0004 LIFT=2.0
0005 C DRAG/IN AS A FUNCTION OF Y
0006 DRAG=-2.0
0007 TORQUE=0.0
0008 TORQUE=-2.0
C
0009 C
0010 GO TO (1,2,3),N
0011 1 FCN=LIFT
0012 GO TO 4
0013 2 FCN=DRAG
0014 GO TO 4
0015 3 FCN=TORQUE
0016 RETURN
0017 4 END
```

```

0001 SUBROUTINE SECT(VX,VZ,WX,WZ,TORO,E,G,XIBAR,ZIRAR,PMI,YLOCAT,ICOUNT
0002 *DY,WT,MX,MZ,S,TPNT,TDISTR)
0003 REAL MOMENT,MX,MZ,MXA,MZA,MXP,MZP,MXFY,MZFY,LDIVT,MAXQZF,MAXQXF
DIMENSION X(32),Z(32),RX(32),RZ(32),TX(32),TZ(32),QXF(319),QZF(319)
*) ,SIGMAX(319),SIGMAZ(319),XX(319),ZZ(319),QCON(319),Q(319),SIGMA(3
*19),YS(10),XP(32),ZP(32),OX(319),QZ(319),QZF(319),ZEFXF(319),XEF
*ZF(319),ZEFZF(319),IDRXZF(319),IDRXF(319),IDRX(319)

```

```

C READ DATA IN. WRITE DATA OUT
C
C IF(YLOCAT.EQ.0.0) GO TO 1
GO TO 16
1 DO 2 I=1,32
2 READ(5,3)RX(I),RZ(I),TX(I),TZ(I)
3 FORMAT(5X,F6.3,9X,F6.3,9X,F6.3,9X,F6.3)
WRITE(6,4)
4 FORMAT(1H1,'THE INPUT DATA WAS READ AS FOLLOWS')
DO 5 I=1,32
5 WRITE(6,6)I,RX(I),RZ(I),TX(I),TZ(I)
6 FORMAT(1X,'RX(',I3,')=',F7.3,5X,'RZ(',I3,')=',F7.3,5X,'TX(',I3
*,')=',F7.3,5X,'TZ(',I3,')=',F7.3)
READ(5,7)YF,YL

```

```

C CALCULATE MIDSPAN LOCATION
C
YM=(YL-YF)/2.
7 FORMAT(5X,F10.5,5X,F10.5)
READ(5,8)RXAC,RZAC,TXAC,TZAC
8 FORMAT(5X,F10.5,5X,F10.5,5X,F10.5,5X,F10.5)
WRITE(6,9)YF,YL,RXAC,RZAC,TXAC,TZAC
9 FORMAT(1X,'THE Y LOCATION OF ROOT AIRFOIL IS ',F9.5
1/, 'THE Y LOCATION OF THE TIP AIRFOIL IS ',F9.5/,
2' THE LOCATION OF THE ROOT AERODYNAMIC CENTER IS ',
37X,'RXAC=',F9.5,5X,'RZAC=',F9.5/,
4' THE LOCATION OF THE TIP AERODYNAMIC CENTER IS ',
57X,'TXAC=',F9.5,5X,'TZAC=',F9.5)
READ(5,982)RHOS,RHOC
982 FORMAT(24X,E10.3,/,24X,E10.3)
WRITE(6,983)RHOS,RHOC
983 FORMAT(1X,'SKIN DENSITY LRS./IN.3 =',E10.3,/,1X,'CORE DENSITY LBS.
*/IN.3 =',E10.3)
READ(5,101)ATANGD,CHAND,E,G,NN
10 FORMAT(15X,F6.5,/,16X,F8.5,/,12X,F8.5,/,22X,E10.3,/,14X,E10.3,/,49
*X,I2)

```

```

C CHANGE ANGLES TO RADIAN. INITIALIZE SKIP VARIABLE
ATTANG=ATANGD*2.*3.14159/360.
CHANG=CHAND*2.*3.14159/360.
ISKIP=0
DO 11 I=1,NN
11 READ(5,12)YS(I)
12 FORMAT(36X,F8.5)
WRITE(6,13)I,ATTANG,CHANG,E,G,NN
13 FORMAT(1X,'SKIN THICKNESS=',F6.5,/, 'ANGLE OF ATTACK=',F7.5,/, ' CH
*ORD ANGLE=',F7.5,/, ' MODULUS OF ELASTICITY=',E10.3,/, ' SHEAR MODUL
*US',E10.3,/, ' NUMBER OF WRITEOUTS=',I2)
DO 14 I=1,NN
14 WRITE(6,15)YS(I)
15 FORMAT(1X,' INFO. ETC. PRINTOUT AT SECTION Y=',F9.3)

```

```

0038 C INITIALIZE SKIN AND CORE VOLUMES
0039 C SVOL=0.0
0040 C CVOL=0.0
16 IF(YLOCAT.EQ.0.0.AND.ISKIP.EQ.0)YLOCAT=YM
C THIS SUBROUTINE, TO SAVE TIME, DOES NOT CALCULATE SHEAR CENTER LOCATIONS EACH
C TIME A SECTION OF THE WING IS EVALUATED. INSTEAD THE WING IS FIRST
C EVALUATED AT MIDSPAN AND ROOT SECTIONS FOR A SHEAR CENTER LOCATION. ALL
C OTHER SECTION SHEAR CENTER LOCATIONS ARE ASSUMED TO LAY ALONG A LINE DRAWN
C BETWEEN THE ROOT SHEAR CENTER AND MIDSPAN SHEAR CENTER
C YLOCAT GIVES SPAN LOCATION
C ISKIP IS A SWITCH WHICH CAUSES THE SUBROUTINE TO EVALUATE
C THE MIDSPAN FIRST AND THEN THE ROOT FOR SHEAR CENTER LOCATIONS
C
C DIRECTION COSINES FOR(A.C. LINE,A LINE L TO THE A.C. LINE AND LYING IN THE
C YZ PLANE,A LINE L TO BOTH OF THESE)
0041 UNIT=SQRT((TXAC-RXAC)**2+(TZAC-RZAC)**2+(YL-YF)**2)
0042 A1=(TXAC-RXAC)/UNIT
0043 B1=(YL-YF)/UNIT
0044 C1=(TZAC-RZAC)/UNIT
0045 A2=SQRT(1./((A1/B1)**2+1.))
0046 B2=-A2*A1/B1
0047 C2=0.
0048 VAR1=-B2/A2
0049 VAR2=-C1*VAR1/(A1*VAR1+B1)
0050 C3=SQRT(1./((1.+VAR1**2+VAR2**2))
0051 B3=-C3*C1/B1
0052 A3=B3*A1/B1
C THE AIRFOIL SHAPE AT SPAN LOCATION YLOCAT IS CALCULATED BY THE EQUATION FOR
C A LINE IN THREE DIMENSIONS.
0053 DO 20 I=1,32
0054 X(I)=(TX(I)-RX(I))*(YLOCAT-YF)/(YL-YF)+RX(I)
0055 Z(I)=(TZ(I)-RZ(I))*(YLOCAT-YF)/(YL-YF)+RZ(I)
0056 XAC=((TXAC-RXAC)*(YLOCAT-YF)/(YL-YF)+RXAC
0057 ZAC=((TZAC-RZAC)*(YLOCAT-YF)/(YL-YF)+RZAC
0058 XP(I)=X(I)
0059 ZP(I)=Z(I)
0060 XACP=XAC
0061 ZACP=ZAC
0062 20 CONTINUE
C THE CORE AREA AND VOLUME IS CALCULATED FOR EACH SECTION
C
0063 AREA1=0.
0064 AREA2=0.
0065 DO 55 I=1,32
0066 J=I+1
0067 IF(I.EQ.32) J=1
0068 DELTAX=(X(J)-X(I)
0069 AVGZ=(Z(J)+Z(I))/2.
0070 IF(DELTAX)54,54,53
0071 AREA1=AREA1+DELTAX*AVGZ
0072 GO TO 55

```

```

0073 54 AREA2=AREA2-DELTA*AVGZ
0074 55 CONTINUE
0075 CAREA=AREA2-AREA1
0076 IF(I=SKIP.EQ.1.OR.ICOUNT.GT.0)CVOL=CAREA*DY+CVOL

```

C THE CENTROID LOCATION, MOMENTS OF INERTIA, PRINCIPAL CENTROIDAL AXIS  
 C ORIENTATION, AND SKIN AREA AND VOLUME ARE CALCULATED AT EACH SECTION.  
 C

```

0077 TANG=0.0
0078 ANG=0.0
0079 24 AREAT=0.0
0080 AXT=0
0081 AZI=0
0082 AXZI=0
0083 XI1=0
0084 ZI1=0
0085 DO 25 I=1,32
0086 J=I+1
0087 IF(1.EQ.32) J=1
0088 DELTAX=XP(J)-XP(I)
0089 DELTAZ=ZP(J)-ZP(I)
0090 DIST=SQRT(DELTAZ**2+DELTAX**2)
0091 XIS=DIST*(T**3)/12.0
0092 ZIS=T*(DIST**3)/12.0
0093 SINANG=DELTAX/DIST
0094 COSANG=DELTAZ/DIST
0095 XIC=XIS*(COSANG**2)+ZIS*(SINANG**2)
0096 ZIC=XIS*(SINANG**2)+ZIS*(COSANG**2)
0097 AREA=DI*ST*
0098 XRARS=(XP(J)+XP(I))/2.0
0099 ZBARS=(ZP(J)+ZP(I))/2.0
0100 AX=AREA*XBARS
0101 AZ=AREA*ZBARS
0102 AXZ=AREA*XBARS*ZBARS
0103 AZSQD=AREA*(ZBARS**2)
0104 AXSQD=AREA*(XBARS**2)
0105 XI=XIC+AZSQD
0106 ZI=ZIC+AXSQD
0107 AREAT=AREA+AREAT
0108 AXT=AX+AXT
0109 AZT=AZ+AZT
0110 AXZT=AXZ+AXZT
0111 XIT=XI+XI1
0112 ZIT=ZI+ZI1
0113 25 CONTINUE
0114 XPBAR=AXT/AREAT
0115 ZPBAR=AZT/AREAT
0116 XIBARP=XIT-AREAT*(ZPBAR**2)
0117 ZIBARP=ZIT-AREAT*(XPBAR**2)
0118 XZIBRP=AXZT-AREAT*XPBAR*ZPBAR
0119 PMIP=XIBARP+ZIBARP
0120 IF(ANG.EQ.0.0)XBAR=XPBAR
0121 IF(ANG.EQ.0.0)ZBAR=ZPBAR
0122 IF(ANG.EQ.0.0)XIBAR=XIBARP
0123 IF(ANG.EQ.0.0)ZIBAR=ZIBARP
0124 IF(ANG.EQ.0.0)XZIBAR=XZIBRP
0125 IF(ANG.EQ.0.0)PMI=PMIP
0126 Y=2.*XZIBRP

```

```

0127 W=ZIBARP-XIBARP
0128 IF(Y.LT.0.001) GO TO 28
0129 ANG=ATAN2(Y,W)/2.
0130 TANG=TANG+ANG
0131 DO 26 I=1,32
0132 XP(I)=XP(I)*COS(ANG)+ZP(I)*SIN(ANG)
0133 ZP(I)=-XP(I)*SIN(ANG)+ZP(I)*COS(ANG)
0134 XACP=XACP*COS(ANG)+ZACP*SIN(ANG)
0135 ZACP=-XACP*SIN(ANG)+ZACP*COS(ANG)
0136 GO TO 24
0137
0138
26 28 TANG=TANG*360./12.*3.14159)
    IF(1SKIP.EQ.1.OP.1COUNT.GT.0) SVGL=AREAT*DY+SVOL

```

C THE MOMENTS, SHEAR FORCES, AND TORQUE ABOUT THE AERODYNAMIC CENTER LOCATION  
 C AT EACH SECTION IS CALCULATED.  
 C

```

0139 ONE=YLOCAT-DY
0140 TWO=YLOCAT
0141 WZA=(FCN(ONE,1)+FCN(TWO,1))/2.
0142 WXA=(FCN(ONE,2)+FCN(TWO,2))/2.
0143 WTA=(FCN(ONE,3)+FCN(TWO,3))/2.
0144 IF(YLOCAT.LT.YL)GO TO 600
0145 VZA=0.0
0146 MZA=0.0
0147 VXA=0.0
0148 MXA=0.0
0149 TORQUE=0.0
0150 GO TO 700
0151 F=YL-YLOCAT
0152 N1=500*F/YL
0153 N2=N1*4/5
0154 N=1
0155
29 CONTINUE
    U=YLOCAT
    H=F/N1
    SUM=FCN(U,N)+FCN(YL,N)
    DO 30 I=2,N1
    U=U+H
    SUM=SUM+FCN(U,N)*2.
    FORCE=H/2.*SUM
    IF(N.EQ.3) GO TO 32
    H=F/N2
    U=H
    UN=H*N2
    US=YLOCAT
    USN=YLOCAT+UN
    SUM=FCN(US,N)*U+FCN(USN,N)*UN
    US=US+H
    DO 31 I=2,N2
    U=U+H
    UL=U-H
    US=US+H
    USL=US-H
    SUM=SUM+2.*FCN(USL,N)*UL+FCN(USL,N)*U+FCN(US,N)*UL
    MOMENT=H/4.*SUM
    GO TO (33,34,35),N
    VZA=FORCE
    MXA=MOMENT

```

600

30

31

32

33

0180

```

0181      GO TO 36
0182      VXA=FORCE
0183      MZA=-MOMENT
0184      GO TO 36
0185      35 TORQUE=FORCE
0186      36 N=N+1
0187      IF(N.LT.4) GO TO 29

C
C   DIRECTION COSINES ORIENT THE MOMENTS AND FORCES PARALLEL TO THE FREE STREAM
C   VELOCITY FROM THE SKEWED AERODYNAMIC CENTER LINE
C
C   MOMENT VECTORS SUPERPOSED ON X,Z,Y AXIS
700 SUB1=B1*WTA
    SUB2=B1*TORQUE+B2*MXA+B3*MZA
    SUB3=A1*TORQUE+A1*WTA*DY/2.+A2*MXA+A3*MZA
    SUB4=C1*TORQUE+C1*WTA*DY/2.+C2*MXA+C3*MZA
    WTA=SUB1
    TORQUE=SUB2
    MXA=SUB3
    MZA=SUB4

C   FORCE VECTORS SUPERPOSED ON X,Z,Y AXIS
    SUB5=A2*MXA+A3*MZA
    SUB6=C2*MXA+C3*MZA
    SUB7=A2*VXA+A3*VZA
    SUB8=C2*VXA+C3*VZA
    WXA=SUB5
    WZA=SUB6
    VXA=SUB7
    VZA=SUB8

C
C   THE MOMENTS AND FORCES ARE ORIENTED WITH RESPECT TO THE X,Y,Z AXIS AND THE
C   XP,Y,ZP PRINCIPAL CENTROIDAL AXIS
C
    TU=ATTANG-CHANG
    VZ=VZA*COS(TU)-VXA*SIN(TU)
    WZ=WZA*COS(TU)-WXA*SIN(TU)
    VX=VZA*SIN(TU)+VXA*COS(TU)
    WX=WZA*SIN(TU)+WXA*COS(TU)
    MZ=MZA*COS(TU)-MXA*SIN(TU)
    MX=MZA*SIN(TU)+MXA*COS(TU)
    THETA=ATTANG-CHANG+TANG
    VZP=VZA*COS(THETA)-VXA*SIN(THETA)
    WZP=WZA*COS(THETA)-WXA*SIN(THETA)
    VXP=VZA*SIN(THETA)+VXA*COS(THETA)
    WXP=WZA*SIN(THETA)+WXA*COS(THETA)
    MZP=MZA*COS(THETA)-MXA*SIN(THETA)
    MXP=MZA*SIN(THETA)+MXA*COS(THETA)

C
C   IF THIS WAS THE NEXT TO LAST SECTION TO BE EVALUATED CALCULATE AND WRITE
C   OUT SKIN AND CORE WEIGHT.
C
    SM1=S-DY
    IF(YLOCAT.EQ.SM1)WSKIN=RHOCS*SVOL
    IF(YLOCAT.EQ.SM1)WCORE=RHOCS*CVOL
    IF(YLOCAT.EQ.SM1)WRITE(6,981)WSKIN,WCORE
    981 FORMAT(1X,'SKIN WEIGHT= ',E12.5/,1X,'CORE WEIGHT= ',E12.5)

C
C   IF THIS IS THE FIRST SECTION TO BE EVALUATED THE PROGRAM CALCULATES THE

```

C SHEAR CENTER AT THE ROOT AND MIDSPAN. TO SAVE COMPUTING TIME ALL OTHER  
 C SHEAR CENTER LOCATIONS ARE CALCULATED BY THE EQUATION FOR A LINE DRAWN  
 C BETWEEN THE ROOT AND MIDSPAN SHEAR CENTERS.

```

0223 IF((YLOCAT.EQ.0.0).OR.(YLOCAT.EQ.YM)).AND.ICOUNT.EQ.0)GO TO 100
0224 ZSC=((YLOCAT-YF)/(YM-YF))*(ZSCM-ZSCF)+ZSCF
0225 XSC=((YLOCAT-YF)/(YM-YF))*(XSCM-XSCF)+XSCF
0226 ZS=ZSC*COS(TANG)-XSC*SIN(TANG)
0227 XS=ZSC*SIN(TANG)+XSC*COS(TANG)
0228 ZSHEAR=ZS-ZACP
0229 XSHEAR=XS-XACP

```

C WITH A SHEAR CENTER LOCATION THE TORQUE IS TRANSFERRED FROM THE AERODYNAMIC  
 C CENTER TO THE SHEAR CENTER

```

0230 TORQ=TORQUE+VZP*XSHEAR-VXP*ZSHEAR
0231 WT=WTA+WZP*XSHEAR-WXP*ZSHEAR

```

C TWISTING DEFLECTIONS WERE CALCULATED FOR EACH SECTION AS A FUNCTION OF THE  
 C SHEAR FLOW DISTRIBUTION IN THE SKIN DUE TO THE TORQUE LOAD.

```

0232 LDIVT=0
0233 DO 573 I=1,319
0234 J=I+1
0235 IF(I.EQ.319)J=1
0236 DELTAX=XX(J)-XX(I)
0237 DELTAZ=ZZ(J)-ZZ(I)
0238 DIST=SQRT(DELTAX**2+DELTAZ**2)
0239 LDIVT=LDIVT+DIST/T
0240 573 CONTINUE
0241 TPNT=TORQ*LDIVT*DY/(4.*CAREA**2*G)
0242 TDISTR=WT*LDIVT*DY**2/(8.*CAREA**2*G)

```

C INFORMATION AT A SECTION SPECIFIED IN THE DATA IS PRINTED OUT.

```

0243 DO 400 I=1,NN
0244 ITEST=YS(I)/DY
0245 IF(ITEST.EQ.ICOUNT)GO TO 62
0246 400 CONTINUE
0247 RETURN

```

C THE FOLLOWING CALCULATES THE SHEAR FLOW DISTRIBUTION, SHEAR CENTER  
 C LOCATION, AND ASSIGNS A SIGN BY NUMBER CONVENTION TO EACH LOCATION

```

0248 100 DO 37 I=1,32
0249 J=10.0*(I-1)
0250 IF(I.EQ.1) J=1
0251 XX(J)=XP(I)
0252 ZZ(J)=ZP(I)
0253 I=1
0254 J=10
0255 DELTAX=XX(J)-XX(I)
0256 DELTAZ=ZZ(J)-ZZ(I)
0257 DX=DELTAX/9.0
0258 DZ=DELTAZ/9.0
0259 DO 38 N=1,8
0260 XX(I+N)=XX(I)+N*DX

```



```

0261 38 ZZ(I+N)=ZZ(I)+N*DX
0262 DO 39 I=10,310,10
0263 J=I+10
0264 IF(I.EQ.310) J=1
0265 DELTAX=XX(J)-XX(I)
0266 DELTAZ=ZZ(J)-ZZ(I)
0267 DX=DELTAX/10.0
0268 DZ=DELTAZ/10.0
0269 DO 39 N=1,9
0270 XX(I+N)=XX(I)+N*DX
0271 39 ZZ(I+N)=ZZ(I)+N*DZ
0272 LDIVT=0
0273 DELXF=0
0274 DELZF=0
0275 CONXF=-VXP/ZIBARP
0276 CONZF=-VZP/XIBARP
0277 QXF(I)=0
0278 QZF(I)=0
0279 DO 40 I=1,319
0280 J=I+1
0281 IF(I.EQ.319) J=1
0282 DELTAX=XX(J)-XX(I)
0283 DELTAZ=ZZ(J)-ZZ(I)
0284 DIST=SQRT(DELTAX**2+DELTAZ**2)
0285 XH=(XX(J)+XX(I))/2.0
0286 ZH=(ZZ(J)+ZZ(I))/2.0
0287 AREA=T*DIST
0288 XCENT=XH-XPRAR
0289 ZCENT=ZH-ZPBAR
0290 QXF(J)=QXF(I)+CONXF*XCENT*AREA
0291 QZF(J)=QZF(I)+CONZF*ZCENT*AREA
0292 QAVXF=(QXF(J)+QXF(I))/2.0
0293 QAVZF=(QZF(J)+QZF(I))/2.0
0294 DELXF=DELXF+QAVXF*DIST/T
0295 DELZF=DELZF+QAVZF*DIST/T
0296 LDIVT=LDIVT+DIST/T
0297 QCONXF=-DELXF/LDIVT
0298 QCONZF=-DELZF/LDIVT
0299 DO 41 I=1,319
0300 QXF(I)=QXF(I)+QCONXF
0301 41 QZF(I)=QZF(I)+QCONZF
0302 C LOCATING MAXIMUM SHEAR FLOWS DUE TO FORCES IN THE X DIRECTION, Z DIRECTION
0303 MAXQZF=QZF(I)
0304 MAXQXF=QXF(I)
0305 DO 42 I=1,319
0306 IF(QZF(I).GT.MAXQZF)IMXQZF=I
0307 IF(QXF(I).GT.MAXQXF)IMXQXF=I
0308 IF(QZF(I).GT.MAXQZF)MAXQZF=QZF(I)
0309 IF(QXF(I).GT.MAXQXF)MAXQXF=QXF(I)
0310 42 CONTINUE
0311 C ASSIGN APPROPRIATE SIGNS TO SHEAR FLOWS
0312 IX=IMXQZF
0313 JX=IX+1
0314 IF(IZ.EQ.319)JZ=1

```

```

0315 IF(IX.EQ.319)JX=1
0316 DELTZZ=ZZ(JZ)-ZZ(IZ)
0317 DELTXX=XX(JX)-XX(IX)
0318 IF(VZP)43,44,45
0319 44 WRITE(6,46)
0320 46 FORMAT(IX,'METHOD OF LOCATING SHEAR CENTER IN ERROR')
0321 RETURN
0322 43 IF(QZF(IZ))61,44,47
0323 45 IF(QZF(IZ))47,44,61
0324 61 DO 48 I=1,319
0325 QZF(I)=-QZF(I)
0326 48 CONTINUE
0327 47 IF(VXP)143,44,145
0328 143 IF(QXF(IX))146,44,147
0329 145 IF(QXF(IX))147,44,146
0330 146 DO 148 I=1,319
0331 QXF(I)=-QXF(I)
0332 148 CONTINUE

C C ASSIGN VALUE TO ZTYPE FOR ONE OF FOUR POSSIBILITIES
C C Z EFFECTIVE FORCE
C C DIRECTION SIGN
C C I TO J / J TO I + / -
C C I TO J / J TO I - / +
0333 ZTYPE=+1.
0334 ZTYPE=-1.
0335 147 IF(DELTZZ)49,44,50
0336 49 IF(QZF(IZ))51,44,51
0337 50 IF(QZF(IZ))210,44,210
0338 210 ZTYPE=+1.
GO TO 211
51 ZTYPE=-1.

C C ASSIGN VALUE TO XTYPE FOR ONE OF FOUR POSSIBILITIES
C C X EFFECTIVE FORCE
C C DIRECTION SIGN
C C I TO J / J TO I + / -
C C I TO J / J TO I - / +
0339 XTYPE=+1.
0340 XTYPE=-1.
0341 211 IF(DELTXX)149,44,150
0342 149 IF(QXF(IX))151,44,151
0343 150 IF(QXF(IX))310,44,310
0344 310 XTYPE=+1.
GO TO 311
151 XTYPE=-1.

C C STARTING AT 1 CALCULATE FORCE COMPONENTS
C C AND ITS MOMENTS ABOUT THE AERODYNAMIC CENTER
C C FOR LOCATION OF THE SHEAR CENTER
0345 311 MXY=0.
0346 MZF=0.
0347 DO 320 I=1,319
0348 J=I+1
0349 IF(I.EQ.319)J=1
0350 QAVXF=(QXF(J)+QXF(I))/2.0
0351 QAVZF=(QZF(J)+QZF(I))/2.0
0352 DELTAX=XX(J)-XX(I)
0353 DELTAZ=ZZ(J)-ZZ(I)
0354 DIST=SQRT(DELTAX**2+DELTAZ**2)
0355 EFXF=QAVXF*DIST
0356 EFZF=QAVZF*DIST

```

```

SINANG=DELTAZ/DIST
COSANG=DELTAZ/DIST
XEFXF(I)=EFXF*COSANG*XTYPE
ZEFZF(I)=EFZF*SINANG*XTYPE
XEFZF(I)=EFZF*COSANG*XTYPE
ZEFZF(I)=EFZF*SINANG*XTYPE
XH=(XX(J)+XX(I))/2.
ZH=(ZZ(J)+ZZ(I))/2.
ZTAC=ZH-ZACP
XTAC=XH-XACP
MZY=MZY-(ZEFZF(I)*XTAC)+(XEFZF(I)*ZTAC)
MXFY=MXFY-(ZEFXF(I)*XTAC)+(XEFXF(I)*ZTAC)

```

C C DIRECTION OF OZF'S

```

IF(ZEFZF(I))430,431,432
430 IF(XEFZF(I))426,427,428
431 IF(XEFZF(I))425,429,421
432 IF(XEFZF(I))424,423,422
421 IDRZF(I)=1
GO TO 433
422 IDRZF(I)=2
GO TO 433
423 IDRZF(I)=3
GO TO 433
424 IDRZF(I)=4
GO TO 433
425 IDRZF(I)=5
GO TO 433
426 IDRZF(I)=6
GO TO 433
427 IDRZF(I)=7
GO TO 433
428 IDRZF(I)=8
GO TO 433
429 IDRZF(I)=9

```

C C DIRECTION OF OXF'S

```

433 IF(ZEFXF(I))530,531,532
530 IF(XEFXF(I))526,527,528
531 IF(XEFXF(I))525,529,521
532 IF(XEFXF(I))524,523,522
521 IDRXXF(I)=1
GO TO 320
522 IDRXXF(I)=2
GO TO 320
523 IDRXXF(I)=3
GO TO 320
524 IDRXXF(I)=4
GO TO 320
525 IDRXXF(I)=5
GO TO 320
526 IDRXXF(I)=6
GO TO 320
527 IDRXXF(I)=7
GO TO 320
528 IDRXXF(I)=8
GO TO 320
529 IDRXXF(I)=9

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0411 320 CONTINUE

C CALCULATE SHEAR CENTER BY BALANCING PREVIOUSLY CALCULATED MOMENTS

```

0412 ZSHEAR=-MXY/VXP
0413 XSHEAR=MZY/VZP
0414 ZS=ZACP+ZSHEAR
0415 XS=XACP+XSHEAR
0416 ZSC=ZS*COS(-TANG)-XS*SIN(-TANG)
0417 XSC=ZS*SIN(-TANG)+XS*COS(-TANG)
0418 IF(YLOCAT.EQ.0.0)ZSCF=ZSC
0419 IF(YLOCAT.EQ.0.0)XSCF=XSC
0420 IF(YLOCAT.EQ.0.0)ISKIP=0
0421 IF(YLOCAT.EQ.YM.AND.ICOUNT.EQ.0)ZSCM=ZSC
0422 IF(YLOCAT.EQ.YM.AND.ICOUNT.EQ.0)XSCM=XSC
0423 IF(YLOCAT.EQ.YM.AND.ICOUNT.EQ.0)ISKIP=1
0424 TORQ=TORQUE+VZP*XSHEAR-VXP*ZSHEAR
0425 QCONST=-TORQ/(2.*CAREA)
0426 DO 59 I=1,319
0427 J=I+1
0428 IF(I.EQ.319) J=1
0429 DELTAX=XX(J)-XX(I)
0430 DELTAZ=ZZ(J)-ZZ(I)
0431 DIST=SQRT(DELTAZ**2+DELTAX**2)
0432 EFC=QCONST*DIST
0433 SINANG=DELTAX/DIST
0434 COSANG=DELTAZ/DIST
0435 XEFC=EFC*COSANG
0436 ZEFC=EFC*SINANG
0437 ZEFF=ZEFC+ZEFZF(I)+ZEFXF(I)
0438 XEFF=XEFC+XEFZF(I)+XEFXF(I)
0439 EFF=SQRT(ZEFF**2+XEFF**2)
0440 Q(I)=EFF/DIST

```

C

C DIRECTION OF  $\phi$ 'S

```

0441 IF(ZEFF)830,831,832
0442 830 IF(XEFF)826,827,828
0443 831 IF(XEFF)825,829,821
0444 832 IF(XEFF)824,823,822
0445 821 IDR(I)=1
0446 GO TO 59
0447 822 IDR(I)=2
0448 GO TO 59
0449 823 IDR(I)=3
0450 GO TO 59
0451 824 IDR(I)=4
0452 GO TO 59
0453 825 IDR(I)=5
0454 GO TO 59
0455 826 IDR(I)=6
0456 GO TO 59
0457 827 IDR(I)=7
0458 GO TO 59
0459 828 IDR(I)=8
0460 GO TO 59
0461 829 IDR(I)=9
0462 59 CONTINUE

```

C

C CALCULATES THE NORMAL STRESS DISTRIBUTION IN THE SKIN AT EACH LOCATION.

```

0463      DO 52 I=1,319
0464      D=XX(I)-XPBAR
0465      V=ZZ(I)-ZPBAR
0466      SIGMAX(I)=-MZP*D/ZIBARP
0467      SIGMAZ(I)=-MXP*V/XIBARP
0468      52 SIGMA(I)=SIGMAX(I)+SIGMAZ(I)
C
C WRITE OUT VALUES CALCULATED
0469      62 WRITE(6,994)
0470      WRITE(6,63)YLOCAT
0471      63 FORMAT(1X,'THE AIRFOIL SHAPE AT SECTION ',F9.3,' IS DEFINED',/,',',
*8Y THE REFERENCE X,Z COORDINATES',20X,'BY THE ROTATED REFERENCE XP
*,ZP AXIS')
0472      DO 64 I=1,32
0473      64 WRITE(6,65)I,X(I),I,Z(I),I,XP(I),I,ZP(I)
0474      65 FORMAT(1X,'X(',I3,')=',F7.3,5X,'Z(',I3,')=',F7.3,5X,'XP(',I3,')=',
*,F7.3,5X,'ZP(',I3,')=',F7.3)
0475      WRITE(6,66)TAND,XAC,ZAC,CHAND,ATANGD,T,XIBAR,ZIBAR,XZIBAR,PMI
0476      661 FORMAT(1X,'THE ANGLE IN DEGREES BETWEEN X AND XP AXIS ',F9.3,/,', T
*THE LOCATION OF THE AERODYNAMIC CENTER X=',F9.3,3X,'Z=',F9.3,/,', C
*HORD ANGLE IN DEGREES ',F9.3,5X,'ANGLE OF ATTACK IN DEGREES ',F9.3
*,/,', SKIN THICKNESS ',F9.3,/,', MOMENT OF INERTIA ABOUT THE X AXIS
*,',E12.5,/,', MOMENT OF INERTIA ABOUT THE Z AXIS',E12.5,/,', PRODUCT
* OF INERTIA ABOUT THE X,Z AXIS ',E12.5,/,', POLAR MOMENT OF INERT
*IA ABOUT THE X,Z AXIS',E12.5)
0477      WRITE(6,662)XBAR,ZBAR,VX,VZ,WZ,MX,TORQUE,TORQ,XSC,ZSC
0478      662 FORMAT(/,'CENTROID LOCATION X=',F9.3,5X,'Z=',F9.3,/,', SHEAR IN TH
*E X DIRECTION',E12.5,/,', SHEAR IN THE Z DIRECTION',E12.5,/,', MOM
*ENT ABOUT THE Z AXIS',E12.5,/,', MOMENT ABOUT THE X AXIS',E12.5,/,
*,' TORQUE ABOUT THE AERODYNAMIC CENTER ',E12.5,/,', TORQUE ABOUT TH
*E SHEAR CENTER ',E12.5,/,', SHEAR CENTER LOCATION X=',F9.3,5X,'Z=',
*,F9.3)
0479      IF(ICOUNT.GT.0)GO TO 500
0480      WRITE(6,994)
0481      WRITE(6,626)
0482      626 FORMAT(1X,32X,'SIGN CONVENTION',/,28X,'NUMBER',5X,'DIRECTION',/,30
*X,'1',8X,'LEFT',/,30X,'2',8X,'UP LEFT',/,30X,'3',8X,'UP',/,30X,'4',
*,8X,'UP RIGHT',/,30X,'5',8X,'RIGHT',/,30X,'6',8X,'DOWN RIGHT',/,30
*X,'7',8X,'DOWN',/,30X,'8',8X,'DOWN LEFT')
0483      WRITE(6,627)
0484      627 FORMAT(/,'30X,'SHEAR FLOWS DUE TO FORCES ACTING ALONG THE XP AXIS'
*,/)
0485      DO 73 I=1,319,5
0486      J=I+1
0487      K=I+2
0488      L=I+3
0489      M=I+4
0490      73 WRITE(6,74)I,IDRXXF(I),QXF(I),J,IDRXXF(J),QXF(J),K,IDRXXF(K),QXF(K
*,L,IDRXXF(L),QXF(L),M,IDRXXF(M),QXF(M)
0491      74 FORMAT(1X,'QXF(',I3,')=',I2,E11.4,3X,'QXF(',I3,')=',I2,E11.4,3X,'Q
*XF(',I3,')=',I2,E11.4,3X,'QXF(',I3,')=',I2,E11.4,3X,'QXF(',I3,')='
*,I2,E11.4)
0492      WRITE(6,994)
0493      WRITE(6,628)
0494      628 FORMAT(/,'30X,'SHEAR FLOWS DUE TO FORCES ACTING ALONG THE ZP AXIS'

```

```

0495      DO 75 I=1,319,5
0496      J=I+1
0497      K=I+2
0498      L=I+3
0499      M=I+4
0500      75 WRITE(6,76)I,IDRXZF(I),QZF(I),J,IDRXZF(J),QZF(J),K,IDRXZF(K),QZF(K)
0501      *),L,IDRXZF(L),QZF(L),M,IDRXZF(M),QZF(M)
0502      76 FORMAT(1X,'QZF(',I3,')=',I2,E11.4,3X,'QZF(',I3,')=',I2,E11.4,3X,'Q
0503      *ZF(',I3,')=',I2,E11.4,3X,'QZF(',I3,')=',I2,E11.4,3X,'QZF(',I3,')='
0504      *,I2,E11.4)
0505      WRITE(6,994)
0506      WRITE(6,663)CAREA,OCNST
0507      663 FORMAT(/,' AREA OF CROSSSECTION ',F9.3,/, ' SHEAR FLOW IN SKIN DUE T
0508      *O TORQUE ABOUT SHEAR CENTER ',E12.5)
0509      WRITE(6,632)
0510      632 FORMAT(/,'30X,'SHEAR FLOWS DUE TO TORQUE AND SHEAR LOADS APPLIED A
0511      *T THE AERODYNAMIC CENTER',/)
0512      DO 67 I=1,319,5
0513      J=I+1
0514      K=I+2
0515      L=I+3
0516      M=I+4
0517      67 WRITE(6,68)I,IDRX(I),Q(I),J,IDRX(J),Q(J),K,IDRX(K),Q(K),L,IDRX(L),
0518      *Q(L),M,IDRX(M),Q(M)
0519      68 FORMAT(1X,'Q(',I3,')=',I2,E11.4,3X,'Q(',I3,')=',I2,E11.4,3X,'Q(',I
0520      *3,')=',I2,E11.4,3X,'Q(',I3,')=',I2,E11.4,3X,'Q(',I3,')=',I2,E11.4)
0521      WRITE(6,994)
0522      WRITE(6,647)
0523      647 FORMAT(/,' NORMAL SKIN STRESSES -(COMPRESSION) +(TENSION)',/)
0524      DO 69 I=1,319,5
0525      J=I+1
0526      K=I+2
0527      L=I+3
0528      M=I+4
0529      69 WRITE(6,70)I,SIGMA(I),J,SIGMA(J),K,SIGMA(K),L,SIGMA(L),M,SIGMA(M)
0530      70 FORMAT(1X,'SIGMA(',I3,')=',E11.4,3X,'SIGMA(',I3,')=',E11.4,3X,'SIG
0531      *MA(',I3,')=',E11.4,3X,'SIGMA(',I3,')=',E11.4,3X,'SIGMA(',I3,')=',E
0532      *11.4)
0533      IF(YLOCAT.EQ.YM)GO TO 72
0534      IF(YLOCAT.EQ.YM)GO TO 72
0535      500 WRITE(6,994)
0536      WRITE(6,71)
0537      994 FORMAT(1H)
0538      71 FORMAT(11X,'YLOCAT',11X,'Z',16X,'X',13X,'TWIST',7X,'ABOUT THE X,Z
0539      *AXIS')
0540      72 IF(ISKIP.EQ.0)RETURN
0541      IF(YLOCAT.EQ.YM.AND.ICOUNT.EQ.0.AND.ISKIP.EQ.1)YLOCAT=0.0
0542      IF(YLOCAT.EQ.0.0.AND.ICOUNT.EQ.0.AND.ISKIP.EQ.1)GO TO 16
0543      RETURN
0544      END

```